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Brief introduction BG 65 SI



1 Description

- Brushless DC - drive with integrated speedcontroller
- 4 digital inputs and 2 digital outputs as well as one analog input
- precast application orientated mode
- Control range 1 bis 7000 min₁
- Control voltage 20 - 50 V
- Integrated encoder with 4096 signals per revolution

2 Specification

Power data

	BG 65x25 SI	BG 65x50 SI	BG 65x75 SI
Nominal voltage (VDC)	24	24	42
Nominal power (W)	65	100	140
Nominal torque(Ncm)	17 (21*)	26 (31*)	40 (47*)
Rated speed (rpm)	3100	3100	2860
Nominal current (A)	4	5,6	4,5
Length (connector/ lead version) in mm	107 / 90	132 / 115	157 / 140
Weight (g)	ca. 950	ca. 1300	ca. 1800

*) The nominal torque depends on the motor's heat dissipation. The tables thus list the values taken in accordance with VDE (the German Electrical Engineers' Association) / EN (European Standard) and taken during the installation of a thermally-conductive steel plate with the dimensions 105x105x10mm (data inbrackets).

Electrical data

Maximum motor speed range	0 ... 7000 U/min
Speed range adjustable	70 ... 4096 U/min
Minimum motor voltage	20 V DC
Maximum motor voltage at 24 V-version	30 V DC
Maximum motor voltage at 42 V-version	50 V DC
Maximum ripple on supply voltage	Max. 5 %
Undervoltage shutdown	< 19 V
Demolition boundary at 24 V- version	> 35 V
Demolition boundary at 42 V- version	> 55 V
Required external fuse	8 AT external
Over-temperature protection	> 100°C at the power output stage
Max. peak current (motor)	27 A
Current consumption of 24 V-logic supply	40 mA (only motors with 42 V- or 60 V-operating voltage)

Mechanical data

Temperature range motor	-20 °C ... +100 °C housing temperature
Recommended environmental temperature range *)	0 °C ... 50 °C
Relative humidity (not condensing)	Max. 90%
Protection class **)	IP50 (in special versions up to IP65)
Connector plug 12-pole ***)	Round connector according DIN 45326, company Binder, series 723

3 Details

The brief introduction describes the mechanical and electrical data, as well as the connector assignment of the drive.

It is to pay attention to the safety regulations and preventive measures which have to be used.

The brief introduction does not contain a manual of the drive. The complete manual BG 65 SI can be requested or is available via download in the internet.

Liability exclusion

For damage or injuries from inappropriate, negligent or wrong handling of the drive, the manufacturer don't be liable.

Modification

Technical changes or changes at the drive may be made only with explicit, written permission of the company Dunkermotoren.

Service & Support

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4 Safety

Proper use

The BG 65 SI is a vendor part and may be used in the configuration described in machines and plant (industrial sector).

The drive must be securely mounted and must only be used with the cables and accessories specified by Dunkermotoren.

The drive may only be put into service after the complete system has been installed with due attention to EMC aspects.

Transport and conditions of storage

Check the drive with distribution for damages. To ensure trouble-free operation, appropriate methods of transport and conditions of storage must be employed.

The drive have to be stored, protected from dust, dirt and moisture.

Pay attention to the climate conditions given in the table „Mechanical data“ (Storage temperature and humidity).

Group of persons

The drive must only be installed and adjusted by qualified persons in accordance with the relevant standards.

Qualified persons are familiar with the relevant standards, rules, and accident-prevention regulations which must be observed when working with such equipment. Qualified persons are those who:

- on the basis of their experience, can recognise and avoid potential dangers;
- are familiar with the accident-prevention regulations for the equipment employed; and
- are able to connect circuits and install equipment in accordance with the standards and regulations.

Ballast circuit

During braking operations, kinetic energy is stored as electrical energy in an intermediate part of the regulation circuit. This can cause excessive voltage in the intermediate circuit, which, in an extreme case, could cause damage to electrical components.

For prevention a bridge rectifier and a smoothing capacitor (Construction unit for the smoothing of voltage fluctuations) should be used.

Warning

If there is frequent heavy braking, the ballast resistor, and in consequence other circuit components, may be overloaded and damaged if appropriate measures are not taken to prevent excessive voltage (see „Smoothing capacitor“, above, possibly external brake resistor).

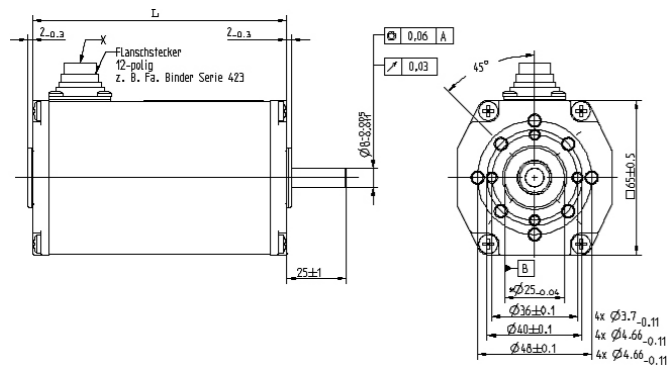


Wiring

Consider the local regulations for wiring, protection and EMC.

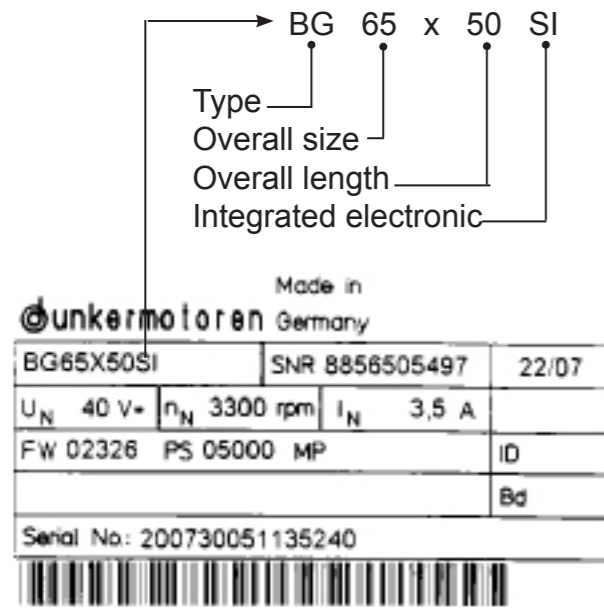
Use only specified cables of the company Dunkermotoren.

5 Drive dimension



	L
BG 65x25 SI	107 ± 0.8
BG 65x50 SI	132 ± 0.8
BG 65x75 SI	157 ± 0.8

6 Identification



SNR = code number U_N = Nominal voltage
 n_N = Rated speed I_N = Nominal current

The identification plate is on the drive and provides for orientation (Exact data are to be read under „Specification“).

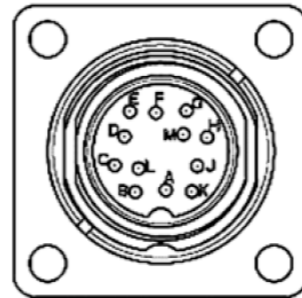
7 Installation/terminal assignment



Attention
 During installation, ensure that connectors are not damaged. Bent pins can cause a short circuit and destroy the drive.

8 Connector plug

Motor power supply and signal interface supply:
 Round plug to DIN 45326, Binder, Serie 723
 The 12-pin drive connector serves for the motor power stage and the electronic supply.



Connection 24 V-motors:

Conector-Pin	Connection	Strand colour of the connecting cable with 12-pole angular connector (*)
E+F	U_E	red (1 mm ²)
D*	IN4	green
M+G	Gnd	black (1 mm ²)
B	IN1	yellow
C	IN2	blue
J	AI+	pink
H	AI-	violet
A	OUT1	orange
K	OUT3	white
L	IN3	brown

Note: At the 42 V-motors the inputs IN3 and IN4 do not exist!

Connection 42 V-motors:

Conector-Pin	Connection	Strand colour of the connecting cable with 12-pole angular connector (*)
E+F	U_E	red (1 mm ²)
D	U_c	green
M+G	Gnd	black (1 mm ²)
B	IN1	yellow
C	IN2	blue
J	AI+	pink
H	AI-	violet
A	OUT1	orange
K	OUT2	white
L	OUT3	brown

(*) Lead colours refers to standard connection cables of Dunkermotoren.

Function of the digital inputs IN1 & IN2:

IN1	IN2	Function
0	0	Controlling not active, output stage not provided with current, no holding torque
1	0	Counter clockwise rotation (motor shaft turns counter clockwise)
0	1	Clockwise rotation (motor shaft turns clockwise)
1	1	Stop with holding torque

Function of the digital inputs IN3 & IN4:

IN3	IN4	Function
0	0	Controlled motor speed mode (70 ... 4096 rpm adjustable via analogue input)
0	1	Uncontrolled operation (70 ... approx. 6500 rpm adjustable via analogue input)
1	0	Fix adjusted, controlled motor speed spd1 = 200 rpm
1	1	Fix adjusted, controlled motor speed spd2 = 2500 rpm

Function of the pulse output OUT1:

The pulse output provides 15 impulses per motor turn. As a result of the generation of the pulses via sampling, a fuzziness of up to 100 ms arises at the flanks, so that a measurement of the pulses duration larger than 1 pulse is not adequate for designation of the motor speed.

Function of the fault output OUT3:

Serves as signal for faults.

/fault	Description
0	fault
1	no fault

The output displays a disturbing signal when reaching a limit value (OUT3=0). Here the protective functions over-temperature protection, undervoltage protection, current limitation and blocking protection are considered.

9 Connection schematic

